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Synopsis

The accurate estimation of peak particle velocity (PPV) is crucial during the design of bench blasting operations in open pit mines, since the vibrations caused by blasting can significantly affect the integrity of nearby buildings and other structures. Conventional models used to predict blast-induced vibrations are not capable of capturing nonlinear relationships between the different blasting-related parameters. Soft computing techniques, *i.e.*, techniques that are founded on the principles of artificial intelligence, effectively model these complexities. In this paper, we use the random forest (RF) algorithm to develop a model to predict blast-induced ground vibrations from bench blasting using 48 data records. The model was trained and tested using WEKA datamining software. To build this model, a feature selection process using several combinations of Attribute Evaluators and Search Methods under the WEKA Select Attributes tab was performed. The correlation coefficient of the actual data and RF model-predicted data was 0.95, and the weighted average of the relative absolute error (RAE) was 10.9%. The RF model performance was also compared to the equivalent-path-based (EPB) equation on the testing data-set, and it was seen that the RF model can effectively be used to predict PPV. The study also demonstrates that the EPB equation is a suitable empirical method for predicting PPV.

Keywords

Blast-induced ground vibrations, peak particle velocity, random forest algorithm, EPB equation.

Introduction

Blasting is the most common means of fragmenting rock in mining and construction projects. In some cases, blasting is performed in close proximity to buildings and other structures, where the vibrations caused can significantly affect the integrity of these structures. The peak particle velocity (PPV) is the most important parameter generally used to evaluate ground vibrations in blasting sites (Jiang *et al.*, 2019). Accurately evaluating and predicting the PPV, and then optimizing the blast design, helps to minimize the damage caused by blasting vibrations (Longjun *et al.*, 2011).

The intensity of blast-induced ground vibrations is commonly evaluated by regression analysis using the Sadaovsk (Li, Ling, and Zhang, 2009), US Bureau of Mines (Duval and Fogelson, 1962), Langefors-Kihlstrom (Langefors and Kihlstrom, 1963), and the Indian Standard (Bureau of Indian Standards, 1973) formulae. The general form of all these conventional methods is presented in Equation [1]:

$$PPV = K(Q^{\beta}/R)^{\alpha}$$
 [1]

where

PPV is peak particle velocity (cm/s)

Q is maximum explosive charge (kg)

R is the distance between the explosion source and the measuring point (m)

K, β , and α are site-specific constants that are related to the blasting conditions and rock characteristics.

There are many factors that influence blast vibrations, and mathematical techniques do not accurately model all these factors. As a result, several other techniques have been developed to find a more efficient method for predicting blast-induced ground vibrations. Many researchers have employed soft computing for this purpose. Soft computing refers to a group of computational techniques that are founded on the principles of artificial intelligence. These methods can effectively handle the complexities that arise from the nonlinear relationships between the variables that influence blasting. Methods that have been explored to improve the study of PPV include:

- ➤ Artificial neural networks (ANNs) (Amnieh, Mozdianfard, and Siamaki, 2010; Amnieh, Siamaki, and Soltani, 2012; Azimi, Khoshrou, and Osanloo, 2019; Das, Sinha, and Ganguly, 2019; Jiang *et al.*, 2019; Kamali and Ataei, 2010; Kosti *et al.*, 2013; Ragam and Nimaje, 2019; Sayadi *et al.*, 2013)
- ➤ Other machine-learning studies (Lawal, Olajuyi, and Kwon, 2021; Longjun *et al.*, 2011)
- Numerical methods (Ducarne *et al.*, 2018; Kumar *et al.*, 2020; Nguyen and Gatmiri, 2007)
- Multivariate analysis (Hudaverdi, 2012)
- ➤ Empirical analysis (Hu and Qu, 2018)
- ➤ Bayesian approach (Aladejare, Lawal, and Onifade, 2022).

Diverse parameters are used differently in building soft computing methods. Das, Sinha, and Ganguly (2019) developed an ANN model utilizing the following parameters: rock density, number of holes, hole diameter, hole depth, burden, spacing, charge length, stemming length, maximum explosive charge per delay, charge, distance of monitoring point from face, Young's modulus, Poisson's ratio, P-wave velocity, and density of explosive. Longjun *et al.* (2011) compared the performance of support vector machines and the random forest (RF) algorithm utilizing the following: maximum amount of charge at one time, total amount of charge, horizontal distance, elevation difference, front row resistance line, presplit penetration ratio, integrity coefficient, angle of minimum resistance line to measured point, and detonation velocity.

Mostly ANNs have been utilized in blast-induced vibration predictions, and it is critical to explore the performance of other machine-learning algorithms. This should be extended by investigating the performance of these algorithms using different blasting and rock mass parameters to effectively model blastinduced ground vibrations. In this paper, the parameters modified by Hu and Qu (2018) in developing their equivalent-path-based (EPB) equation have been used to build a PPV prediction model using the RF algorithm. This method was chosen because Hu and Qu implemented a unique way of interpreting the distance between the blasting and vibration measurement points, along with the inclusion of pertinent properties such as those concerning explosive energy release and rock mass properties. To optimize the performance of the model, a feature selection procedure is also utilized to develop the best feature subset. The RF model performance is then compared to the results from the EPB equation.

Literature review

A brief description of the EPB equation and RF is presented in this section. The underlying rationale of choosing to compare these two methods for predicting PPV was that unique parameters were introduced in deriving the EPB equation and thus it is fundamental to use these parameters in developing machine-learning models. This may improve the accuracy of PPV prediction. RF was chosen because it is a widely used algorithm, and the same data-set that was used to test the EPB equation was used to develop the RF model, as will be described later.

EPB equation

The general form of the blast-induced ground vibration formula is illustrated in Equation [1]. To modify and improve the predictive power of this equation, Hu and Qu (2018) developed the EPB equation. Blast-induced ground vibrations arise from the energy released by the detonating explosives. Since the energy is related to the type of explosive, Hu and Qu concluded that the energy release properties of the explosive should be included in the final

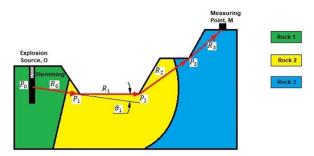


Figure 1—The equivalent path (red line) on a bench-like surface (Hu and Qu, 2018)

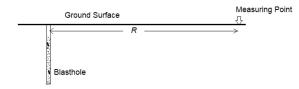


Figure 2—Schematic of blast vibration measurement on a flat surface

formula. The explosion heat of the explosive (Qv) was the parameter suggested to represent this relationship. Hu and Qu also proposed the use of an equivalent propagation path (*i.e.* a series of straightline segments P_0P_1 , P_1P_2 , P_2P_3 , .., P_xP_{x+1} as indicated in Figure 1) of the seismic wave, as opposed to the horizontal distance previously used

The concept of equivalent path seems reasonable as opposed to taking the distance travelled by the seismic wave as a straight line (as assumed in previous studies). If the measurements are taken on a flat surface, the idea of representing the path travelled by the seismic wave as a straight line is valid (Figure 2).

However, the topography on an open pit mine (Figure 1) is more complex and it is very unlikely that the vibration waves will travel along a straight line to the geophones positioned on the slopes or anywhere outside the pit. The seismic wave will travel, within the ground, to the measuring points and it will never be propagated through the void above the pit floor and sides. Hu and Qu therefore assumed that the shortest possible path that the seismic wave travels beneath the ground can be utilized as the distance from detonation to measuring point. This shortest distance was then used to represent *R* in Equation [1]. This was termed the 'equivalent distance', and the procedures for determining this distance are given in Hu and Qu (2018). However, the interactions between blast-holes and their influence on the equivalent path was not considered.

Impedance of the rock mass was also included in formulating the EPB equation. The impedance was defined by Hu and Qu (2018) as $\frac{1}{2}$

$$z = \rho c_m / \eta \tag{2}$$

where

z is the impedance

 ρ is the rock density (g/cm³)

 c_m is the longitudinal wave propagation velocity of the rock mass (m/s)

η is the integrity factor of the rock mass $[η=(c_m/c_r)^2]$ and c_r is the longitudinal wave propagation of the rock (m/s)].

The PPV and impedance were said to be negatively correlated. Since impedance is the effective resistance of the rock mass to propagation of the waves, it follows that the higher the impedance of the rock mass the lower the PPV. Following this parametric analysis, the EPB equation (Equation [3]) was proposed (Hu and Qu, 2018) as:

$$PPV = K \left[\frac{(Q.Q_v)^{\frac{1}{3}}.(1 + \cos\theta_i)}{\sum_{i=0}^{i=n} (2R_i\rho_i c_{mi}/\eta_i)} \right]^{\alpha}$$
 [3]

where

i = 0, 1, 2, 3...

PPV is peak particle velocity (cm/s)

Q is the maximum explosive charge fired per delay (kg)

 Q_v is the explosion heat of the explosive at constant volume (kJ/kg) R_i is the equivalent distance (m)

 θ_i is the intersection angle of the wave propagation direction to the ground surface at Pi (degrees)

 ρ_i is the density of the rock on the equivalent path (g/cm³) η_i is the integrity coefficient of the rock mass.

The general structure of the EPB equation is very similar to that of Equation [1]. However, the parameters in the EPB equation have been improved and modified to closely represent the phenomena. Of much importance is the representation of R in Equation [1] as the equivalent distance, R_i . The explosion heat of the explosive (Q_v) has also been accommodated in the EPB equation. Site-specific rock mass characteristics that influence how seismic waves travel in rocks have also been included in the equation. These rock mass characteristics were chosen by Hu and Qu as the impedance and the density of the rock. A detailed analysis of the development of the EPB equation and how θ_i can be incorporated into the equation is presented in Hu and Qu (2018).

RF algorithm

To easily comprehend the brief description of the RF algorithm, definitions of a few machine-learning technical terms that will feature in the narrative are presented here.

- ➤ Attributes/features/predictors These are basically the columns of a data-set, and they represent a separate measurable characteristic of the parameter being investigated. In other words, these are a characteristic of an instance (individual rows in the data-set).
- ➤ Base learners Individual models that constitute an ensemble.
- ➤ Bootstrap sampling A statistical technique that involves random subsampling with replacements.
- Class The parameter that is being predicted (in this case the PPV).
- ➤ *Classifier* An algorithm that learns from the data and then makes predictions.
- Decision tree (DT) A flow chart-like tree that displays the several outcomes from a sequence of decisions. It is used as a decision-making tool from given data. DTs have three main parts: a root node, internal nodes, and leaf nodes. The root node is the starting point of the tree, and it contains all the input data. An internal node can comprise two or more branches (arrows connecting nodes) and is related with a decision function. A leaf node represents the target/output of a given input vector and denotes a class label. Figure 3 is a simple example of a DT showing when it is possible to blast in an open pit (Yes) and when it is not possible to blast (No) given various weather combinations.
- ➤ Ensemble A group of different base models whose individual predictions are combined to produce one optimal predictive model
- ➤ *Entropy* A technique used in machine-learning to determine how a DT chooses to split data at nodes.
- ➤ Gini impurity Another technique which performs similar functions as entropy to build DTs.

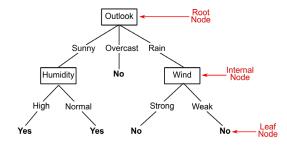


Figure 3—Flow chat of a DT structure

➤ Overfitting – This is a challenge in machine-learning where an algorithm can fit the training data very well but fails to generalize to make predictions on new data. In DTs it is caused by developing too deep trees (trees with many internal nodes).

Thus, RF is a machine-learning algorithm that consists of growing an ensemble of DTs for accomplishing classification/ regression on a given data-set. Ensemble learning defines all the techniques that use numerous base learners (DT₁, DT₂, ..., DT_k in Figure 4), then combines their individual outputs to produce a single classifier. The base learners combine their outputs by a majority vote technique in classification or through averaging in regression. The RF algorithm is described as an variation of bagging which creates a forest of de-correlated trees and averages their predictions (Breiman, 2001). DT models commonly suffer from overfitting (high variance) and thus averaging out predictions from multiple DTs leads to a decrease in overall variance. The practise of growing these DTs is centred on bagging (bootstrap aggregation), which is a procedure for decreasing the variance of an estimated prediction function. Here, bagging principally encompasses generating several data subsets from the training data by bootstrap sampling (random subsampling with replacement) and selecting random subsets of predictor variables. Each of these data subsets, of similar distribution, is then utilized to independently train a DT.

Additionally, for each tree, only a random subset of predictors/ features is used for developing the decision model. For each tree thus created, a predictor is selected to accomplish a decision-split at a particular node. This is generally performed based on either the information gain/entropy or the Gini impurity that selects the best predictor for that node. This procedure is iterated at each node in a DT and consequently several trees are trained. Ultimate prediction decisions are reached based on averaging (for regression) or majority voting (for classification) of individual tree predictions.

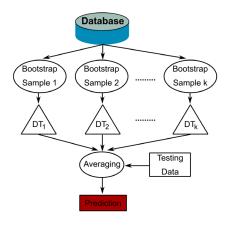


Figure 4—Structure of an RF algorithm for regression

Since data subsampling and predictor subsampling for each tree is carried out randomly on a forest of trees, this algorithm is termed RF. Figure 4 is an example of the structure of an RF algorithm for regression.

Data-set

The data-set utilized to evaluate the usefulness of the RF algorithm in predicting blast-induced ground vibrations was developed from the seismic monitoring measurements carried out by Hu and Qu (2018) at Si-Jia-Ying iron ore mine in China. This mine is a largescale open pit operation which uses multi-hole millisecond delay bench blasting. The features of the data-set and their corresponding notations are listed in Table I. In this case the PPV is the class attribute. This data-set was chosen for the current study because it is the same as that used to develop and test the EPB equation. This consistency will ensure that the comparisons undertaken between the EPB equation and the RF model will be reasonable and reliable.

A total of 48 instances/data-points forms the data-set, as indicated in Table II.

Table I					
Features comprising the data-set					
Feature	Description	Units			
Q_Em	Maximum explosive charge fired per delay for emulsion	kg			
Q_ANFO	Maximum explosive charge fired per delay for ANFO	kg			
Q _v _Em	Explosion heat of explosive at constant volume for emulsion	kJ/kg			
Q _{\nu} _ANFO	Explosion heat of explosive at constant volume for ANFO	kJ/kg			
R_i	Equivalent distance from point of detonation to measuring point	m			
c_m	Longitudinal wave velocity of the rock mass	m/s			
Cr	Longitudinal wave velocity of the rock	m/s			
ρ	Density of the rock	g/cm ³			
η	Integrity coefficient of the rock mass $(\eta = (c_m/c_r)^2)$	-			
PPV	Peak particle velocity	cm/s			

Table II	-								
Data-set									
Q_Em (kg)	Q_ANFO (kg)	Q _v _Em (kJ/kg)	Q _v _ANFO (kJ/kg)	R _i (m)	<i>c_m</i> (m/s)	<i>c_r</i> (m/s)	ρ (g/cm ³)	η (-)	PPV (cm/s)
540	360	3200	3840	289.24	3.980	5.17	3.052	0.593	1.09
540	360	3200	3840	382.14	3.980	5.17	3.052	0.593	0.58
540	360	3200	3840	634.58	3.980	5.17	3.052	0.593	0.29
0	750	0	3840	149.86	3.945	5.01	2.577	0.620	2.74
0	750	0	3840	220.59	3.945	5.01	2.577	0.620	1.61
0	750	0	3840	648.85	3.702	5.16	3.188	0.515	0.13
450	0	3200	0	357.12	3.537	5.07	3.019	0.487	0.60
450	0	3200	0	289.47	3.537	5.07	3.019	0.487	0.97
450	0	3200	0	298.45	3.702	5.16	3.188	0.515	0.80
270	450	3200	3840	553.66	3.945	5.01	2.577	0.620	0.43
270	450	3200	3840	553.66	3.945	5.01	2.577	0.620	0.49
270	450	3200	3840	741.59	3.945	5.01	2.577	0.620	0.25
0	450	0	3840	115.87	3.980	5.17	3.052	0.593	3.15
0	450	0	3840	115.87	3.980	5.17	3.052	0.593	3.15
0	450	0	3840	453.41	3.702	5.16	3.188	0.515	0.20
0	450	0	3840	525.28	3.702	5.16	3.188	0.515	0.22
400	0	3200	0	211.49	3.702	5.16	3.188	0.515	1.03
400	0	3200	0	104.76	3.537	5.07	3.019	0.487	4.81
400	0	3200	0	221.05	3.537	5.07	3.019	0.487	1.47
400	0	3200	0	268.41	3.537	5.07	3.019	0.487	1.44
0	480	0	3840	470.39	3.702	5.16	3.188	0.515	0.34
0	480	0	3840	447.12	3.702	5.16	3.188	0.515	0.42
0	480	0	3840	376.82	3.702	5.16	3.188	0.515	0.70
0	480	0	3840	354.03	3.702	5.16	3.188	0.515	0.66
0	480	0	3840	337.21	3.537	5.07	3.019	0.487	0.63
0	480	0	3840	262.48	3.537	5.07	3.019	0.487	1.57
0	480	0	3840	147.77	3.537	5.07	3.019	0.487	4.01
0	480	0	3840	517.29	3.702	5.16	3.188	0.515	0.17

Table II (c	ontinued)								
Data-set									
Q_Em (kg)	Q_ANFO (kg)	Q _v _Em (kJ/kg)	Q _v _ANFO (kJ/kg)	<i>R_i</i> (m)	<i>c_m</i> (m/s)	<i>c_r</i> (m/s)	ρ (g/cm ³)	η (-)	PPV (cm/s)
0	480	0	3840	423.72	3.702	5.16	3.188	0.515	0.31
0	480	0	3840	400.92	3.537	5.16	3.188	0.470	0.39
0	480	0	3840	309.38	3.702	5.16	3.188	0.515	0.59
0	480	0	3840	122.32	3.980	5.17	3.188	0.593	4.34
0	480	0	3840	61.31	3.537	5.07	3.019	0.487	9.89
0	480	0	3840	119.24	3.537	5.16	3.188	0.470	4.16
700	0	3200	0	56.21	3.980	5.17	3.052	0.593	14.65
400	0	3200	0	394.89	3.702	5.16	3.188	0.515	0.28
400	0	3200	0	413.52	3.702	5.16	3.188	0.515	0.19
400	0	3200	0	430.51	3.702	5.16	3.188	0.515	0.15
400	0	3200	0	483.05	3.702	5.16	3.188	0.515	0.13
0	450	0	3840	102.20	3.980	5.17	3.052	0.593	4.82
0	450	0	3840	133.71	3.980	5.17	3.052	0.593	2.23
0	450	0	3840	285.21	3.980	5.17	3.052	0.593	0.46
0	450	0	3840	301.00	3.980	5.17	3.052	0.593	0.43
0	450	0	3840	321.78	3.980	5.17	3.052	0.593	0.44
0	450	0	3840	232.92	3.702	5.16	3.188	0.515	0.46
0	420	0	3840	153.24	3.702	5.16	3.188	0.515	3.40
0	420	0	3840	171.88	3.702	5.16	3.188	0.515	3.42
0	420	0	3840	216.99	3.702	5.16	3.188	0.515	1.92

RF model formulation

The PPV prediction model was developed using Waikato Environment for Knowledge Analysis (WEKA) software (Hall et al., 2009). WEKA is a handy and powerful machine-learning and data-mining software application that can assist users to understand acquired data better. The software incorporates powerful data analysis tools that can be used to extract useful information from large sums of data and develop machine-learning models.

Feature selection

Raw machine-learning data-sets consist of a mixture of features/ attributes, some of which are irrelevant to making accurate predictions. Thus, one of the most important exercises in building machine-learning models is to identify the most influential attributes to include in the model. The process of selecting relevant features from the data is called feature selection. In the WEKA software platform this procedure is performed under the *Select Attribute* tab in WEKA Explorer. Figure 5 is a screenshot of the WEKA home screen with the *Explorer* tab marked in red.

When the *Explorer* tab is selected the dialog indicated in Figure 6 is displayed. The *Preprocess* tab is used to load the data-set into the software, the *Classify* tab is available to the user to enable the construction of different machine-learning models for prediction and classification tasks and the *Select Attributes* tab is used for



Figure 5—Screenshot of WEKA home screen

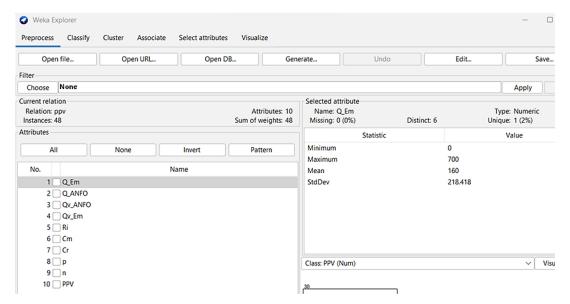


Figure 6-WEKA Explorer dialog

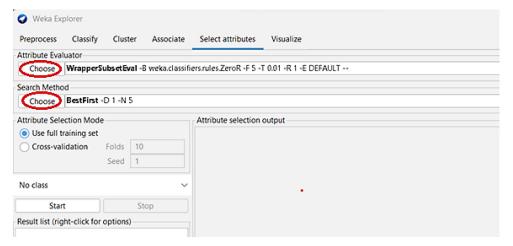


Figure 7—Select Attributes screenshot

feature selection. The *Select Attributes* tab hosts all the techniques necessary to accomplish feature selection. Figure 7 shows the dialog that's displayed to the user when the *Select Attributes* tab is selected. The *Choose* tabs (circled in red) enable the user to select different combinations of *Attribute Evaluators* and *Search Methods* and with the data-set preloaded into the software, the best feature subset is displayed in the *Attribute Selection Output* window.

In WEKA, feature selection is basically divided into two parts (Attribute Evaluator and Search Method). Each of these two sections presents several techniques for accomplishing the feature selection process. Attribute Evaluator is the technique by which each attribute (also called a column or feature) in a data-set is weighed in the context of the output variable (also known as the class). Search Method, on the other hand, navigates several combinations of features in the data-set to arrive at a short list of selected features. Each Attribute Evaluator technique should be used together with a Search Method, and some Attribute Evaluator techniques require the use of specific Search Methods.

The techniques used to perform feature selection in this study are described in Tables Ill and IV.

Table V indicates the combination of techniques used to select the best features for the RF model.

Based on the outcomes in Table V and from analysis of variables as they are used in empirical formulae, the RF model was trained and tested using the following features: R_i , Q_Em , Q_ANFO , Q_{v_ANFO} , Q

RF model

In supervised learning, the performance of a classifier needs to be measured on a given data-set before using it to predict the class of a new project (Zhou, Xibing, and Hani, 2015). To satisfy this criterion, the original data-set is randomly split into two subsets: a training set and a testing set. The training set is used to construct the model and to set the model parameters, while the testing set is used as an independent validation set for assessing the performance

Table III	Table III					
Search methods	Search methods used for feature selection					
Search method	Description					
GeneticSearch	Performs a search using the simple genetic algorithm. Genetic algorithm is a search-based optimization method that is based on the principles of genetics and natural selection.					
BestFirst	Searches the space of attribute subsets using a method called greedy hill climbing. Hill climbing involves either adding or removing of a feature from the data-set at a time. <i>BestFirst</i> may start with the empty set of attributes and add attributes (forward search) or start with the full set of attributes and remove attributes (backward search). If the addition or deletion of a feature does not change the predictive performance of the model, that feature is assumed redundant.					
ExhaustiveSearch	Achieves a comprehensive search through the space of attribute subsets, beginning with an empty set of attributes. It registers the best subset found.					
GreedyStepwise	Executes a greedy forward or backward search through the space of attribute subsets. May start with no/all features or from an arbitrary point in the attribute space. Breaks when the addition/deletion of any remaining features results in a decrease in evaluation.					
Ranker	Ranks features according to their individual assessments.					

Table IV Attribute evaluators used for feature selection			
Attribute evaluator	Description		
WrapperSubsetEval	Assesses sets of attributes by utilizing a learning scheme. Cross-validation is exploited to approximate the accuracy of the learning scheme for a set of attributes.		
CorrelationAttributeEval	Evaluates the worth of a feature by determining its correlation with the class variable.		

and predictive power of the model. In this study, the data-set was split into 70% training set and the remaining 30% was used as the testing set.

In WEKA, hyperparameter tuning is very important when building a model. Hyperparameters, in machine-learning, are a set of parameters that control the behaviour of a model, and these parameters are set/tuned before the training of a model starts. The tuning of these parameters is important because it determines how well a model is going to learn from the training data, thus enabling best performances to be achieved. The key hyperparameter for RF is the number of attributes to consider at each split point. In WEKA this parameter is controlled by the *numFeatures* attribute. In the previous feature selection exercise, six features were selected and

Table V					
Feature selection com	binations and featu	ire subsets			
Attribute evaluator	Search method	Set of attributes			
	GeneticSearch	R _i , Q_Em			
Magne ou Culont Fund	BestFirst	R_i			
WrapperSubsetEval	ExhaustiveSearch	Q _ANFO, R_i , c_m , η			
	GreedyStepwise	R_i			
CorrelationAttributeEval	Ranker	R_i , Q_Em, Q_{ν} _ANFO, Q_ANFO, η , c_m			

thus the best model involved using all these parameters. Therefore, *numFeatures* hyperparameter was set to 6 as it yielded the highest correlation coefficient. The other hyperparameters were left on default settings.

The RF model performance was then compared to the EPB equation to evaluate its predictive power and possibility of future use when employing the parameters from the EPB equation as dataset features.

Results and discussion

The aim of this investigation was to utilize the parameters that constitute the EPB equation and develop and evaluate the performance of the RF algorithm from a data-set formulated from

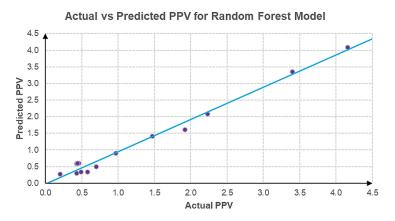


Figure 8—RF model performance on the testing set

these parameters. These parameters are equivalent distance (R_i) , maximum explosive charge per delay (Q), explosion heat of the explosive (Q_v) , and longitudinal wave velocity of the rock mass (c_m) .

The correlation coefficient of the RF model was 0.95, indicating that this model is suitable for predicting blast-induced ground vibrations using equivalent distance (R_i) , maximum explosive charge per delay (Q), explosion heat of the explosive (Q_v) , and longitudinal wave velocity of the rock mass (c_m) as model parameters. The model-predicted PPVs are plotted against the actual values in Figure 8. The agreement is excellent, demonstrating that the RF model is fitted well on the training data-set. As previously highlighted, the model was built by splitting the data into 70% training set and the remaining 30% as the testing set. Thus, 14 data-points were available to test the model.

WEKA also gives a summary of the predictive errors of the model, including mean absolute error (MAE), root mean squared error (RMSE), and relative absolute error (RAE). If the RMSE and MAE are zero, then the model will be perfect, *i.e.*, both values should be minimized. The RF model and the EPB equation results were compared on the test set as indicated in Table VI. Instead of the arithmetic mean, the overall RAE for each set of predictions was computed using the weighted average (Equation [4]) because this approach is reasonably appropriate for regression problems where statistical dispersion is expected between data-points.

$$Overall \ RAE = \sum_{i=1}^{n} \frac{RAE_i \times Actual \ PPV_i}{Actual \ PPV_i}$$
 [4]

It can be seen from Table VI that the predicted values and actual values obtained from RF model are of relatively low comparative error. The overall RAE for the RF model was 10.9%, indicating that the model is sufficiently capable of predicting blast-induced vibrations within a reasonable range of errors.

The RF model has better prediction capabilities than the EPB equation. This is indicated by an overall RAE of 10.9% for the RF model against 14.8% for the EPB equation. The RF model performs better because it is a soft computing technique and can capture nonlinear relationships between the various blasting-related parameters. The slightly lower prediction performance of the EPB equation can be attributed to the inability of mathematical methods to capture the nonlinear relationships between multiple influencing parameters.

The EPB equation has demonstrated that it can produce results that are not far out of range. Good corelation, in general, is indicated by errors of 10% or lower. The 10.9% RAE achieved by the RF model is reasonably close to 10% and the slightly higher margin could be attributed to the relatively small data-set used to train and test the model. It would be of great value to combine the data-set used here with similar data from Zimbabwe and neighbouring regions in order to undertake further studies. This would have the potential to improve the prediction of PPV using the RF algorithm.

To visualize the comparison more clearly, values of PPV for both models were plotted as shown in Figure 9. The result proves that the established RF model is reasonable and reliable in predicting PPV for bench blasting using equivalent distance (R_i) , maximum explosive charge per delay (Q), explosion heat of the explosive (Q_v) , and longitudinal wave velocity of the rock mass (c_m) as predictor variables. Figure 9 shows that the RF model gives a better prediction of the PPV on the test data-set.

The relationships of the four parameters selected for the model with PPV are briefly described as follows.

The prime factor is the equivalent distance (R_i) . There is a direct relationship between equivalent distance and the PPV as it appeared in all the methods used for feature selection. However, this parameter had an individual correlation

Table VI Actual data compared to RF model and EPB equation predictions						
**	1,000	EPB equa	ation	RF model		
No.	Actual PPV	Predicted PPV	RAE (%)	Predicted PPV	RAE (%)	
1	0.46	0.58	26.1	0.60	30.4	
2	0.58	0.76	31.0	0.34	41.4	
3	0.70	0.45	35.7	0.49	30.0	
4	0.97	0.64	34.0	0.90	7.2	
5	0.49	0.46	6.1	0.34	30.6	
6	1.47	1.41	4.1	1.42	3.4	
7	1.92	1.42	26.0	1.61	16.2	
8	0.20	0.27	35.0	0.28	40.0	
9	2.23	2.34	4.9	2.08	6.7	
10	0.43	0.53	23.3	0.58	34.9	
11	4.16	3.58	13.9	4.08	1.9	
12	3.40	3.66	7.6	3.36	1.2	
13	0.44	0.47	6.8	0.60	36.4	
14	0.43	0.46	7.0	0.30	30.2	
Overall, RAE		14.8% 10.9%				

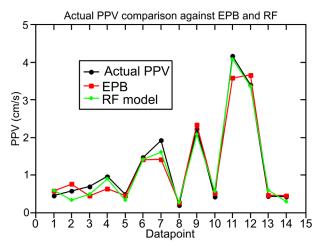


Figure 9—Comparison of measured and predicted data for the EPB equation and RF model

coefficient of -0.66 with PPV. Logically, this is because the magnitude of the vibration naturally decreases away from the detonation point.

- The second factor is maximum explosive charge per delay (Q). The magnitude of PPV is directly proportional to Q. An increase in the quantity of explosives used during blasting results in stronger ground vibrations being caused.
- The vibrations also depend on the energy properties of the individual explosives used, expressed as the explosion heat of the explosive (Q_v). The greater the energy contained in an explosive, the more likely it is to cause stronger ground vibrations.
- Finally, the site-specific characteristics of the rock mass play a key role. This is represented by the longitudinal wave velocity of the rock mass (c_m) . This parameter, plus the density of the rock (ρ) , influences the impedance of the rock mass and the PPV is inversely proportional to ground impedance.

A complex relationship among predictor variables can complicate the prediction of PPV in blasting activities. Therefore, selecting a robust method to develop a PPV prediction model that can cover all the inherent complexity of the problem is very important. RF for regression, in most cases, shows lower average errors and superior predictive performance compared to the other advanced regression algorithms. In this study, RF has proved to be an accurate predictor of PPV in bench blasting scenarios, based on the features chosen for evaluation. However, this should be further verified by integrating other local data-sets with the one used in this study.

Conclusions

Very accurate estimation of PPV is crucial for the design of appropriate bench blasting practices in open pit mining projects, since the vibrations caused by blasting can significantly affect the integrity of nearby buildings and other structures. Conventional methods have been used to predict these blast-induced vibrations. Artificial neural networks (ANNs) have also been developed, resulting in more accurate predictions. To fully understand this phenomenon, it is critical to explore different machine-learning algorithms and evaluate their performances using different sets of predictors (model input parameters). A random forest (RF)

model was developed using equivalent distance (R_i) , maximum explosive charge per delay (Q), explosion heat of the explosive (Q_v) , and longitudinal wave velocity of the rock mass (c_m) as predictor variables. The RF model was found to consistently predict PPV to within a reliable range of accuracies. The model displayed a correlation coefficient, between actual and predicted PPV values, on the test set of 0.95 and an overall relative absolute error (RAE) of 10.9%. The performance of the RF model was compared to that of the equivalent-path-based (EPB) equation. The EPB equation yielded an overall RAE of 14.8%, and thus RF model displayed better prediction capabilities. This study also confirms the usefulness of the EPB equation, as well as the effectiveness of the parameters used in the EPB equation, in formulating more comprehensive data-sets for future use with various algorithms.

The outcomes of this study can be applicable to open pit mines in Zimbabwe and the neighbouring regions. This can be done by integrating local databases into the data-set and using a similar approach as described in this study. This may improve the performance of the RF model. Further studies are necessary to confirm this proposition.

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Author contributions

DN: conceptualization, methodology, software, writing - original draft preparation; BB: writing - reviewing and editing; NR: software, writing - reviewing and editing.

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